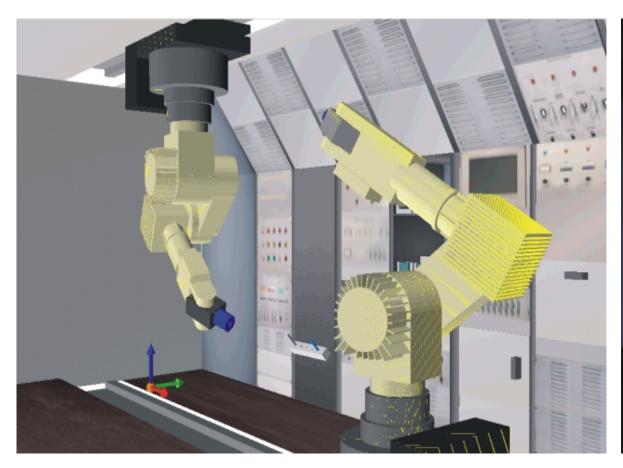
# Robotics is spearheading Smart Production – but we need to deliver, too

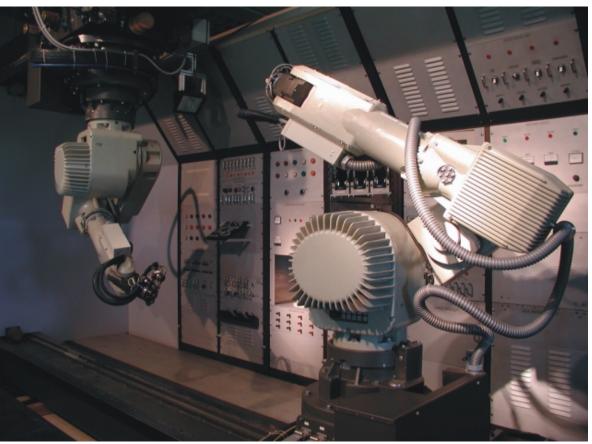
ICINCO 2018 Porto, Portugal 29 – 31 July 2018



### Robot simulation and robot control

\*sigh\* ... my first "digital twin"







### Overview

### **Technologies**

From robot control and simulation to "digital twins" and Smart Production

Transfer, trust and agility

Trying harder to bridge the gap between academia and industry

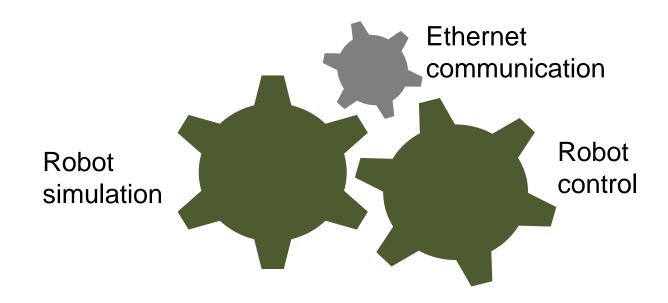




# **Technologies**

# **System components**

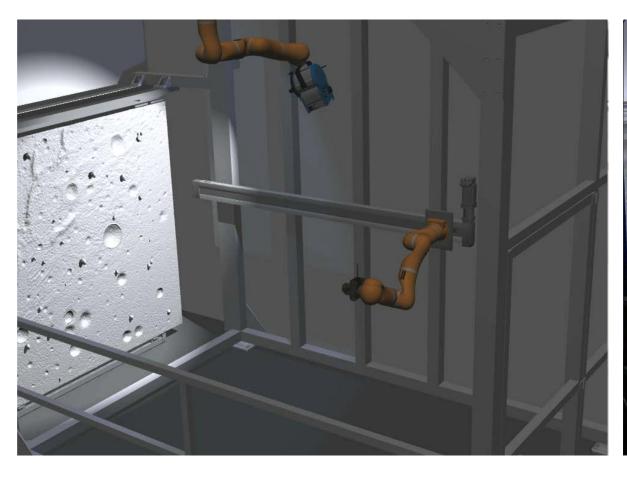
Robot simulation, monitoring and control

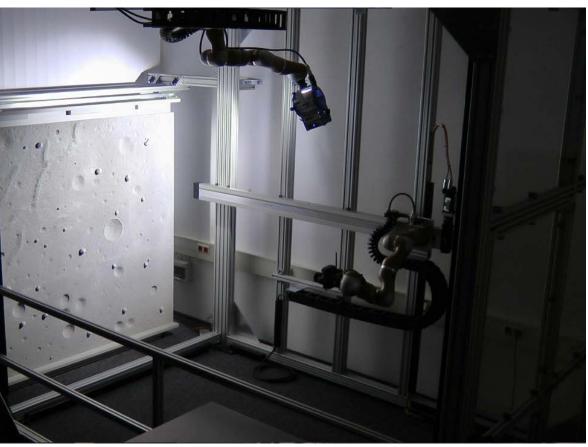




## Simulation-based system development

Mockup for optimization of approach trajectories for DLR



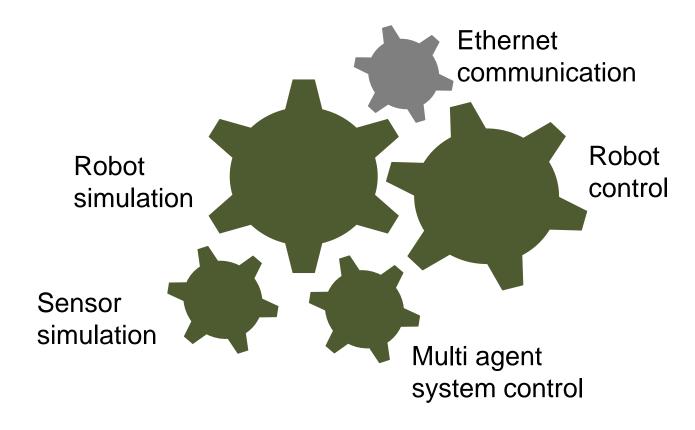






## **System components**

...plus sensor simulation and MAS control





## Simulation-based system development

R&D and operator training for the state of North-Rhine Westfalia (NRW)



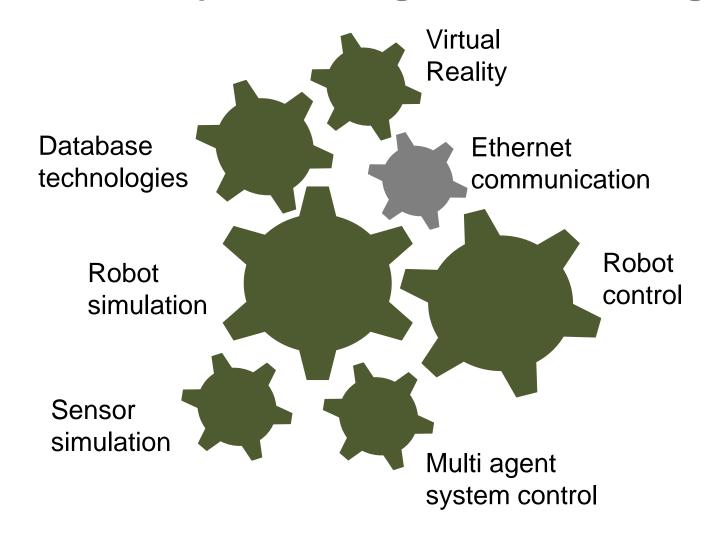






## **System components**

DB technologies and VR to pull in, manage and visualize large environments

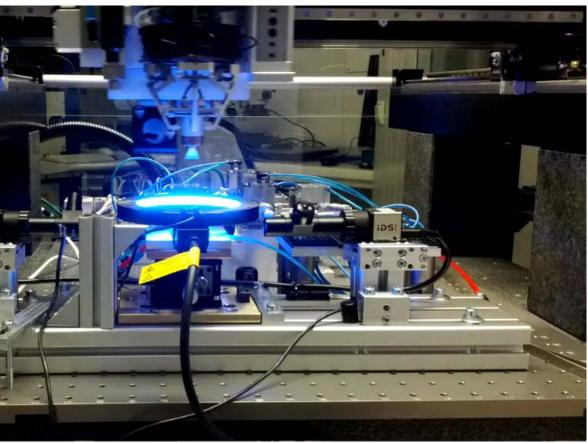




## Simulation-based system development

Virtual commissioning for micro-optical assembly stations



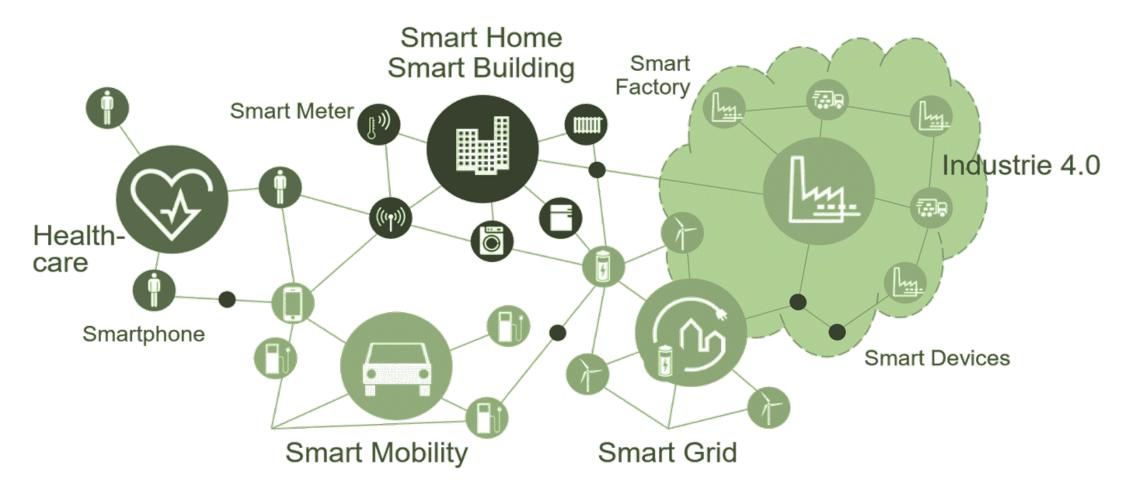






### **Smart Production in context**

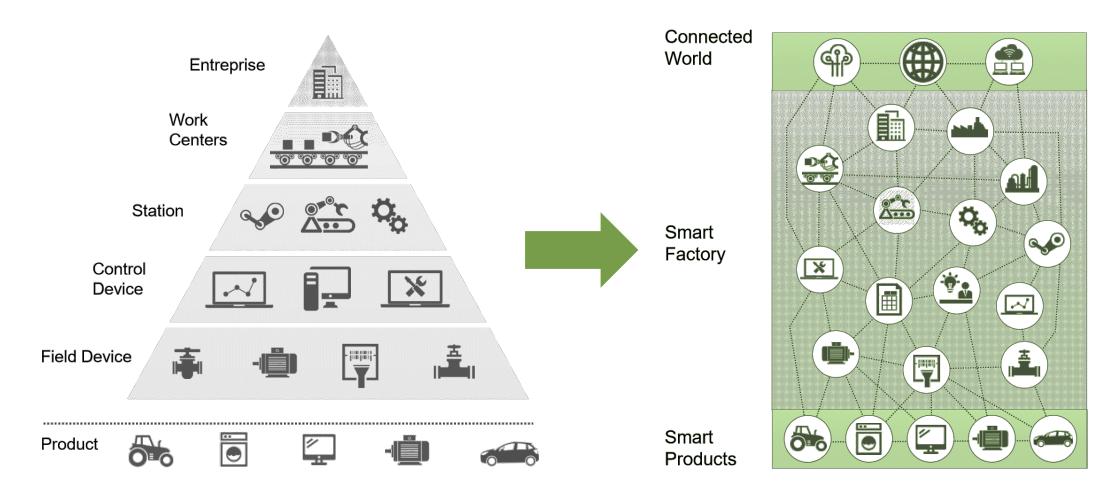
IoT shapes "Smart X"





### Breaking existing hierarchies

Smart Production redefines horizontal and vertical integration schemes





## Data-oriented view on digital twins

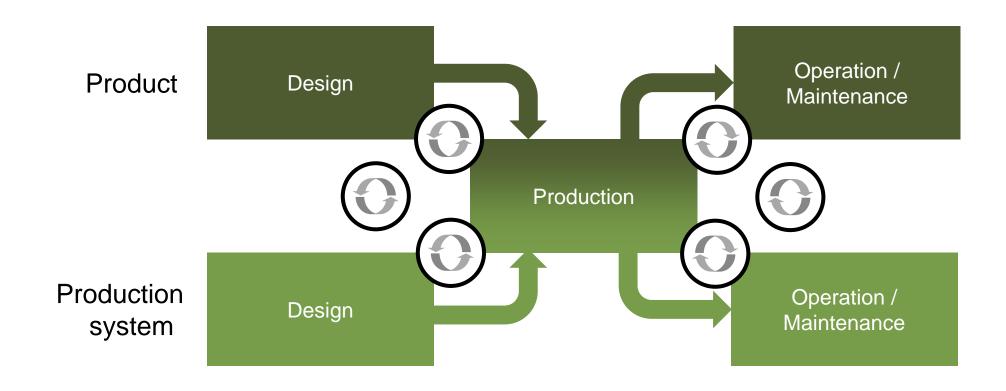
aka "Administrative shell"

Process program Order Process parameters Customer requirements Data Digital Digital **Physical** Twin Twin system <Public> <Private> Control Process status Production progress Quality report • Product location



## Production-oriented view on digital twins

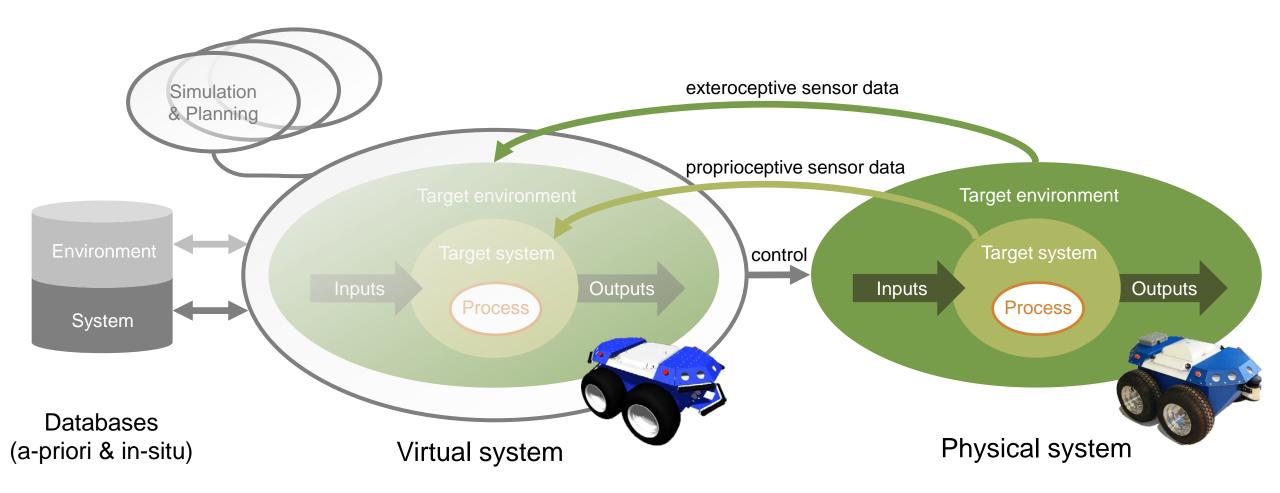
Optimization potentials based on digital twins



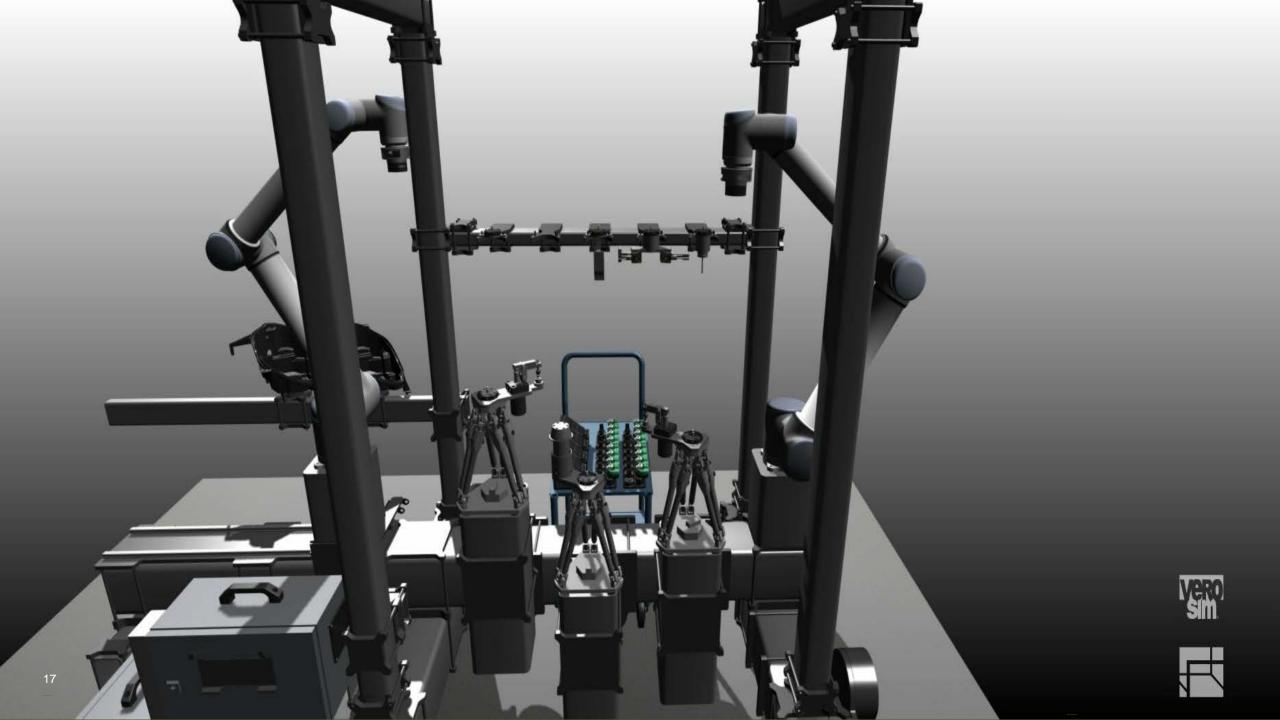


# System-oriented view on digital twins

resp. digital twins in robotics



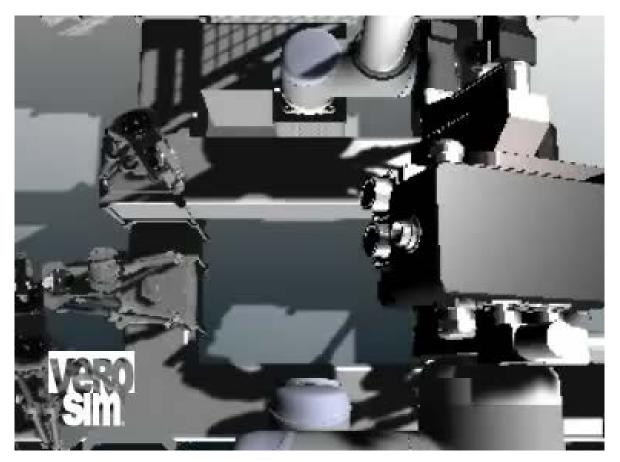


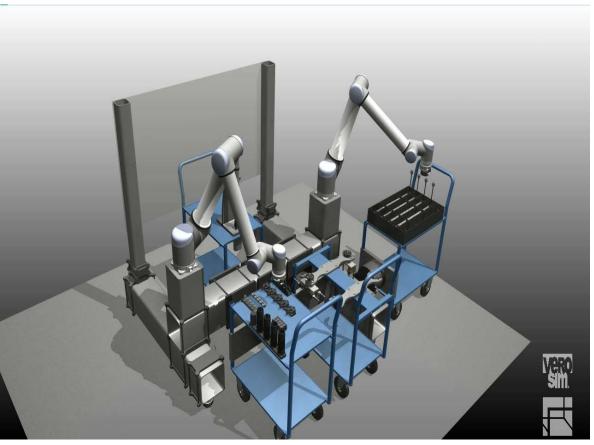




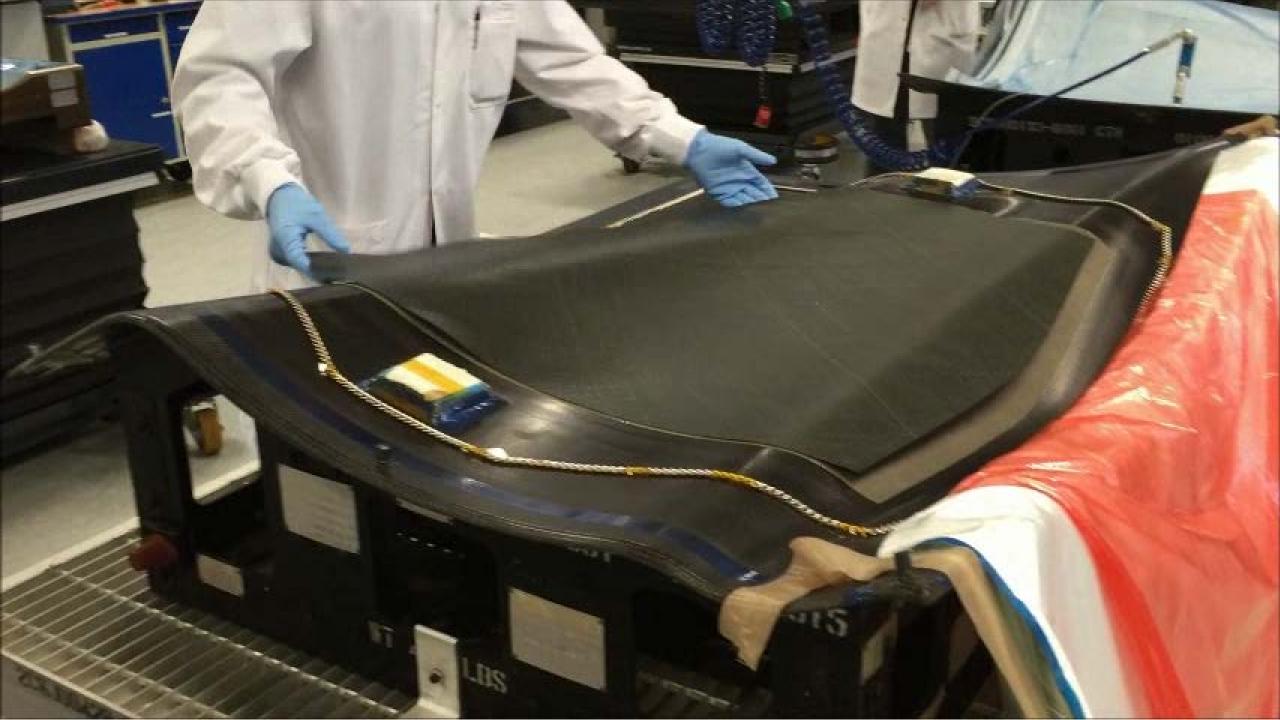
## Optimization of equipment poses

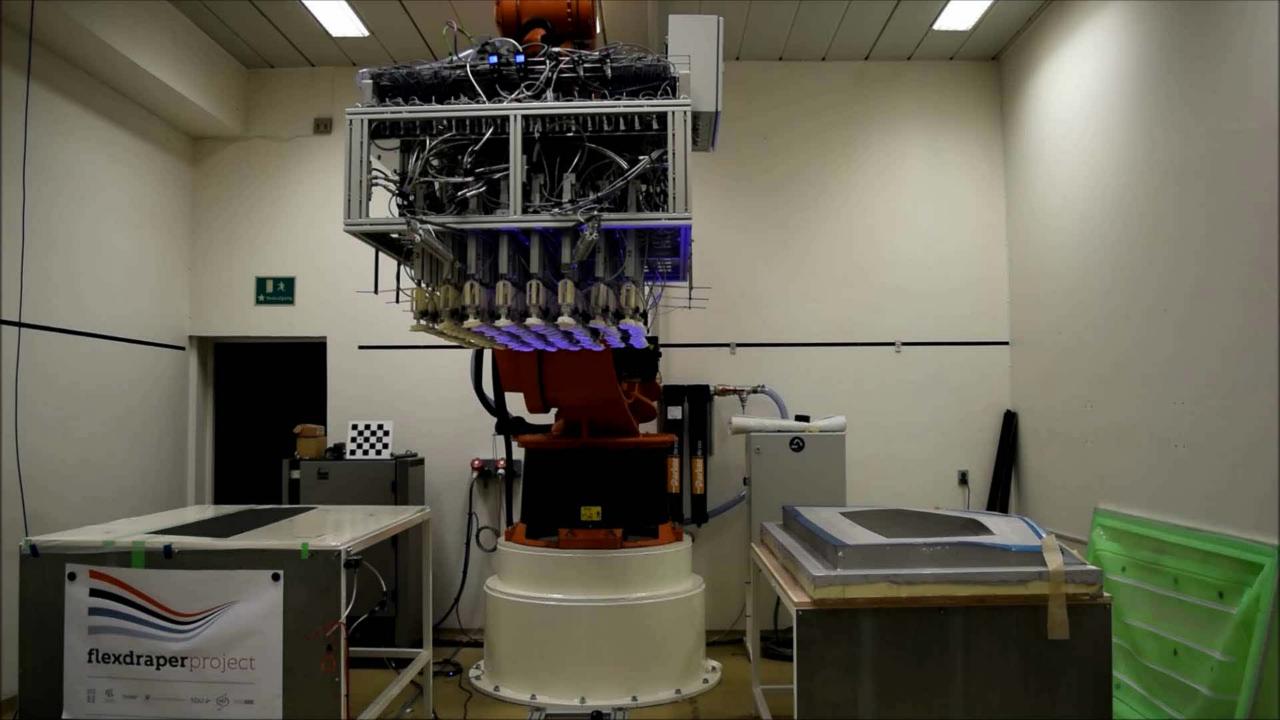
e.g. camera and robot positioning in ReconCell





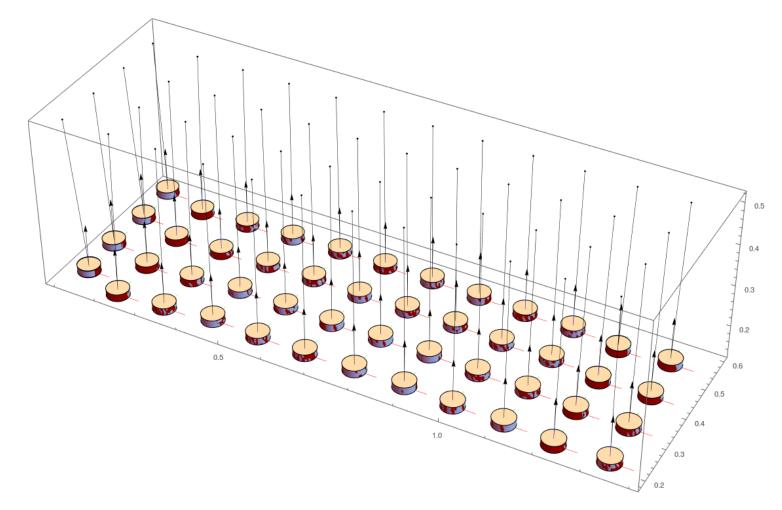






# Optimization of layup strategies

Piston motion patterns in FlexCell





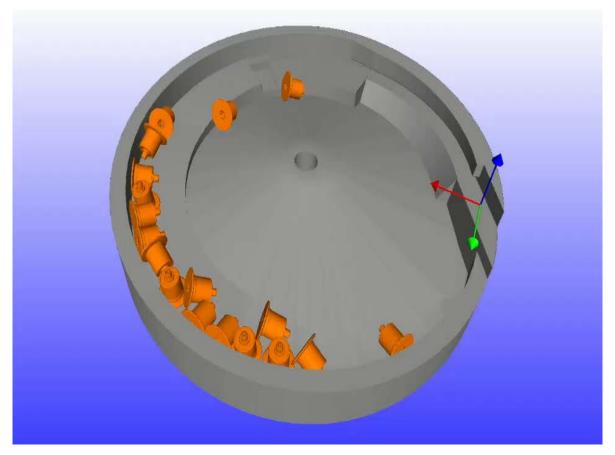
## Details on our approach in FlexCell

Ole W. Nielsen, Christian Schlette and Henrik G. Petersen: Fast and Simple Model for Free Hanging, Pre-impregnated Carbon Fibre Material Proc. of the 15th Int. Conf. on Informatics in Control, Automation and Robotics (ICINCO), Vol. 1, pp. 7, 2018.



## Simulation of other automated components

e.g. vibratory bowl feeders



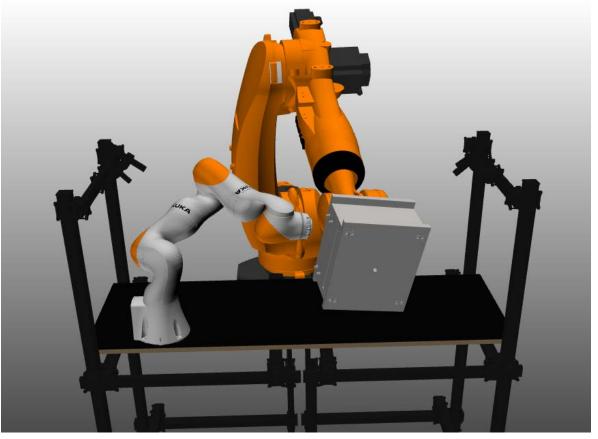




### **NEW:** Human-robot collaboration

e.g. assembly of injection molds for LEGO









# Transfer, trust and agility































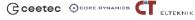






Eabinplant





























































































Laptics Ivs













































OMPANIE































TÂKE ÖN

ROBOTICS

Venture

Funding





































































DIRA



























BEng

S

Electronics and

Computer Engineering

Global Management and

Manufacturing

Integrated Design

and Managemen

Mechanical Engineering

Software Technology





















**VÆKST**HUS













BOREAN

### **ODENSE**

Public Family Funding Offices



SDU 4

UNIVERSITY OF SOUTHERN DENMARK

Business Loan and Bank Angels (100+) Financing

110+ mill. Euros invested in 2016/2017

### SDU 🏠

WelfareTech work in DENMARK

- MSc Applied mathematics
- Electronics Energy Technology

Mathematics

- Manufacturing Engineering
- Mechatronics Technology Rohot Systems

- - Mechanical Mechatronics
  - · Physics and Technology Product Development and Innovation
- · Information Technology - Product Design · Learning and Experience

- LILLEBAELT Academy Profession AP
  - Automation Technology Computer Science IT Technology · Multimedia Design and Communication Production Engineer
  - Bachelor BA · E-Concept Development
    - PBA Software Development · Product Development and Technology Integration Web Development



### SYDDANSK **ERHVERVSSKOLE** Electricity Automation and IT Automatics Electrician

- Industrial Operator Industrial Technician (+EUX)

Technical Designer





SIMAC

Bachelor

· Marine Engineer



















### Augmented reality · Artificial intelligence

DANISH TECHNOLOGICAL







### · Department of Public Health

### Organisation (RIO)

Faculty of Science

Department of Mathematics and

Faculty of Health Sciences

Department of Sports Science and

· Department of Clinical Research

Clinical Biomechanics

Computer Science (IMADA)



- and Robotic Technology Knowledge Center for Health and Welfare Technology
- =PHVERVSSKOLE Knowledge Center for Automation and Robotic Technology







- Electrical Power Engineering Computer science
  - · Engineering Robot Systems (Advanced Robotics Technology and Drone Technology)
- · Welfare Technology

· Operations Management

Software Engineering

### Continuing Education Academic Education Diploma







RESI



### Safety Activities

### Implementation of solutions Dissemination, training

### and education

### · Analysis and consultancy

SDU Engineering Operations Management

### · SDU Software Engineering · SDU Electrical Engineering · SDU Embodied Systems for Robotics and Learning SDU Health Informatics and Technology

Faculty of Engineering

· SDU Innovation and Design Engineering

The Maersk Mc-Kinny Møller Institute

The Mads Clausen Institute

SDU Mechatronics

TEK Innovation

SDU Robotics

· SDU UAS Centre

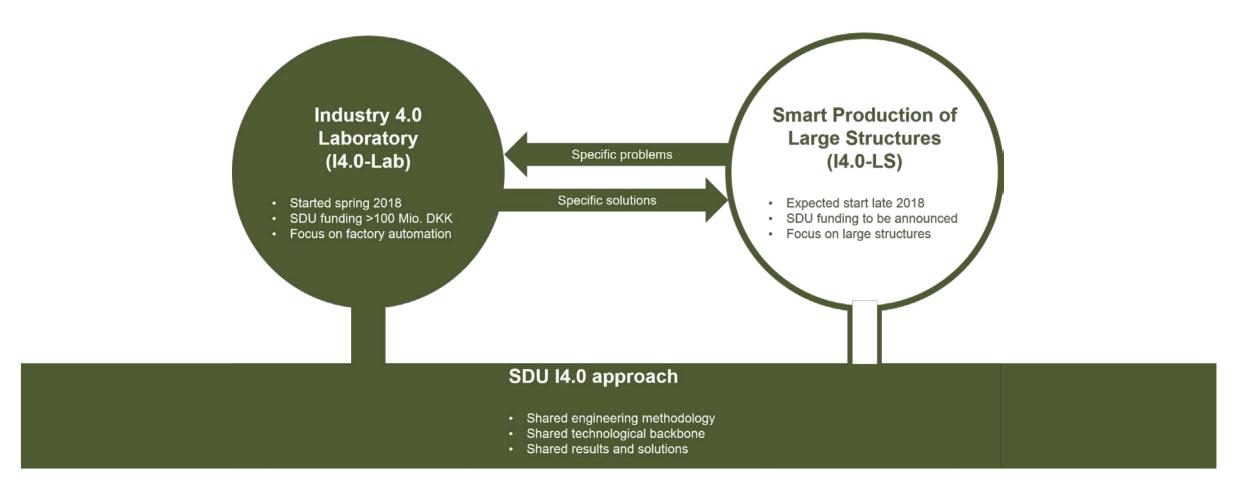
Department of Technology and Innovation SDU Mechanical Engineering





### 14.0-Lab and 14.0-LS

Our complementary I4.0 initiatives for different audiences





### 14.0-Lab and 14.0-LS

Our initiative to start a "reactor" with companies





# We need to improve - trust and agility

- Realistic results and outcomes
- Continuous, reliable partnerships
- Rapid and robust developments
- Clear IPR management
- Clear administrative processes
- Short response times



## Thank your for your attention

Christian Schlette
Associate Professor

SDU ROBOTICS
The Mærsk Mc-Kinnev Mersk M

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